

Smart2Go

H2020-ICT-02-2018 Flexible and Wearable Electronics

Smart2Go

Smart and Flexible Energy Supply Platform for Wearable Electronics

Starting date of the project: 01/01/2019 Duration: 36 months

= Design Contest Handbook =

Version 1.0



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About us

Smart2Go is a project funded by the **EU Horizon 2020** research and innovation programme. The aim of the Smart2Go project is the creation of an autonomous energy-supply platform. Based on the results of the project it will be possible to use a wearable without caring about recharging over its entire lifetime.

The Smart2go project is creating the world's first fully **R2R printed and assembled autonomous energy management and supply platform** (ESP) with high number of discrete components bonded and embedded on flexible plastic substrate.

Half-way through the Smart2Go project, all components of the platform have been successfully developed. With its different components and functionalities, ESP will be able to serve many different applications in the area of **flexible and wearable electronics**.

Smart2Go includes **top EU innovation performers** (researchers and companies) involved in flexible electronics and energy scavenging and storage, as well as 2 partners with very challenging product use scenarios, validating the platform as suitable for multiple needs.

In addition, the Smart2Go External Advisory Board (EAB) is setup with the aim to receive support in the following aspects:

- 1) Exploring new applications and interaction with the end-users;
- 2) Interaction with industrial integrators and manufacturers;
- 3) Standardization and pre-normative activities and
- 4) Networking, clustering and interaction with SMEs associations.



DESIGN CONTEST - HANDBOOK

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1. Introduction

In order to provide information as clearly as possible, the Organizer is providing the datasheets contains products specifications.

The following scheme is showing how the platform interacts with the applications and the harvesting.



For further information or support please contact Organizer.

2.1. Short Description of the Component

The **Energy Supply Platform** is managing the energy flow between harvester applications and storage components.

2.2. Specifications

Table 1: Energy Supply Platform specifications

Energy Supply Platform		
Pads for energy storage Pads for energy storage Microcontroller unit with an accelerometer sensor Pads for external devices		
Mechanical Speci	fications	
Length	120 mm with flexible battery	
Width	50 mm	
Hight	1.3 mm	
Bending radius	60 mm	
Other	The interconnection between the ESP and the battery must be handled	
footuros	carefully.	
Connectivity Specifications		
Connectivity Spec	Earnala ChimpElay housing ritch 1 27 rest	
(type)	remate Chappelex housing, plich 1,27 mm	
(type)	Mala Crime Elan connectore having flat white	
into the peelson	Male ChilipPlex connectors naving that cables	
ппо ше раскаде		
Safety advice		
Organization		
Pieces available	10	

Timing of	if additional samples are required, we will check availability separately.	
making the		
pieces available		
Electrical Specific	cations	
Input voltage	Energy harvester: 50mV-5V	
Input current	max. 90 mA	
Output voltage	3.3Vcc from the energy harvester and 3.3V from the microcontroller pins	
Output current	max. 80mA from harvester, max. 15mA from MCU	
Others	Internal memory: 192 KB Flash, 24 KB RAM	
Other Specifications		
Communication	Bluetooth 5	
Special features	Digital I2C bus available for additional external sensors. Supply voltage 3.3V	
Instruction of	The platform is programmed by the Owner (here VTT). Operation needs to be	
usage	determined in advance.	
Communication	Software coding is done by VTT. Please provide basic function of the system.	
software		

3.1. Short Description of the Component

The **Microbattery** is the main energy storage device connected to the platform.

3.2. Specifications

Table 2: Microbattery specifications

Microbattery		
Mechanical Specifications		
Size	Without connecting taps:	
Length	75mm	
Width	50mm	
Hight	0.45mm	
Bending radius	Max. 1.5cm	
Connectivity Specifications		

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Connectors	Positive Electrode: Al-tap	
(type)	Negative Electrode: Ni-tap	
Safety advice		
Organization		
Pieces available	50 pieces	
Timing of	Lead time 1 Month	
making the		
pieces available		
Electrical Specifications		
Input voltage	Max. 4.2V	
Input current	Max. 90mA	
Output voltage	Min. 2.8V	
Output current	Max. 90mA	
Others	Capacity: 55mAh	
Other Specifications		
Communication	For the physical battery, a disclaimer of liability has to be signed before shipping	

4.1. Short Description of the Component

The **Supercapacitor** is capable of providing high output power for short time.

4.2. Specifications

Table 3: Supercapacitor specifications





Figure 1: Schematic structure and fabricated supercapacitor

Mechanical Specifications		
Size	5 cm by 6 cm	
Length	6 cm	
Width	5 cm	
Hight	0.5 mm	
Bending radius	0.5 cm	
Other	Dual cell, printed, flexible, laminated, etc.	
mechanical		
features		
Connectivity Spee	cifications	
Connectors	Connector such as alligator clips	
(type)	Conductive tape such copper tape	
	Conductive ink pastes such as silver	
Safety advice		
Organization		
Pieces available	10 or more	
Timing of	Dec or early Jan 2022 (Or depends on the requirements)	
making the		
pieces available		
Safety handling	• Be aware not apply over-voltage to the supercapacitor.	
and precautions	• Do not disassemble, crush, or smash the supercapacitor.	
	• Avoid high temperature, high humidity, and direct contact with corrosive and toxic substances.	
	• In case if body skin contacts with electrolyte or electrode, it is	
	recommended to wash the skin with excess of running water.	
	Care should be taken while handling device.	
Electrical Specifications		
Capacitance	3 – 5 mF	
ESR	< 3 Ω	
Input voltage	2.5 V/cell	
Leakage current	0.1 μΑ - 0.3 μΑ	
Input current	>1A	
Others	High power density, long life cycle, fast charge-discharge	
Other Specifications		

Special features	Organic electrolyte (Propylene carbonate)
	• Environmentally friendly, thermally stable, wide temperature range
	Low-cost printing
	Energy storage device
	• Peak power to portable devices
	• Flexible
	Mechanical and electrical reliable
Instruction of	• The positive and negative sign should be checked before making
usage	supercapacitor connections. This will prevent short circuit / damage to
-	the device.
	• Avoid bending and handle device with care.
	• Do not overcharge the supercapacitors (2.5 V/cell)
	• Dispose the supercapacitor if its overheated, dried, bulge, leakage
	electrolyte etc.

5.1. Short Description of the Component

The **Energy harvesting: Photovoltaics** is harvesting the energy from ambient light sources.

5.2. Specifications

 Table 4: Energy harvesting: Photovoltaics specifications

Energy harvesting: Photovoltaics		
HARA A REFA.		
Mechanical Speci	fications	
Total Size	170mm x 50mm	
Length	30mm active / 50mm total	
Width	123mm active / 170mm total	
Hight	0,29 mm	
Bending radius	15mm	
Connectivity Specifications		
Connectors	crimps	
(type)		
Cables included	no	
into the package		
Safety advice		
Organization		

0	100
Sm	ort /l_o
- NUL	

Pieces available	Yes, for 30mm design, few tens of pieces available		
Timing of	6 to 8 weeks for a new run		
making the			
pieces available			
Electrical Specific	Electrical Specifications		
	1000W/m ²		
	30mm	100mm	
Output voltage	ge 7,3 V		
Output current	29,4 mA	98 mA	
Pmax	144 mW	480 mW	
Vmax	6 V		
Other Specifications			
Special features	Operating temperature: -10°C to 60°C		
Instruction of	Positive terminal side = Asca barcode side		
usage			

6.1. Short Description of the Component

The **Energy harvesting: Thermoelectrics** is harvesting energy from electric differences.

6.2. Specifications

Table 5: Energy harvesting: Thermoelectrics specifications

Energy harvesting: Thermoelectrics			
Mechanical Speci	Mechanical Specifications		
Size	12 generators, each of an area of 13 cm ²		
Length	1 generator: 13 cm.		
Width	1 generator: 1 cm		
Hight	1 generator: 135 cm		
Bending radius	1 generator: 1 cm lengthways (bending along the length, as shown in photo above)		
Other	12 individual TEGs can be arranged in different configurations geometrically,		
mechanical	connected with wires between each one as user sees fit.		
features			
Connectivity Spee	cifications		

Connectors	Cu mesh	
(type)		
Safety advice		
Electrical Specifications		
Output voltage	260 mV open circuit voltage (of 12 in series – can be altered by arranging in	
	series/parallel) at a temperature gradient of 25 K	
Output current	140 uA closed circuit current (of 12 in series - can be altered by arranging in	
	series/parallel) at a temperature gradient of 25 K	
Others	260 mV open circuit voltage (of 12 in series - can be altered by arranging in	
	series/parallel) at a temperature gradient of 25 K	
Other Specifications		
Instruction of	Need to apply the generators so the long sides are exposed to a 25 K	
usage	temperature difference between each long side.	

7.1. Short Description of the Component

The **Energy harvesting: Mechanical Energy** is harvesting energy from mechanical movement to electrical energy.

7.2. Specifications

Table 6: Energy harvesting: Mechanical Energy



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Size	Different geometries available (see picture) based on an A4 Design; Sensor
	areas between approx. 3.14 cm ² and 16 cm ²
Length	Approx. 4.4 cm – 7.6 cm
Width	Approx. 1.28cm – 4.3 cm
Hight	Approx. 135µm (125µm PET Substrate plus approx. 10µm printed sensor)
Connectivity Specifications	
Connectors	TE Connectivity / AMP: 5-520315-2 (will be provided)
(type)	
Cables included	No
into the package	
Safety advice	
Organization	
Pieces available	1 to 10 sheets
Timing of	Few days
making the	
pieces available	
Electrical Specifications	
Input voltage	None, active sensor element
Input current	None, active sensor element
Output voltage	mV to few volt depending on excitation
Output current	nA - µA depending on excitation
Other Specifications	
Instruction of	Application specific instructions will be provided
usage	